

Be Part of Livermore's Vision for Safer Streets

Livermore Vision Zero Action Plan (VZAP)

Community Meeting (In-person)

The City is developing a Vision Zero Action Plan (VZAP) which will be a comprehensive strategy to reduce and eventually eliminate traffic fatalities and severe injuries. Recognizing that traffic deaths and severe injuries are preventable, the VZAP aims to prioritize safety, creating a more sustainable and livable city for all.



Your Input is important to us!

Community outreach was held on January 28th to introduce the Vision Zero Action Plan and share how the City is working to improve traffic safety. The project team discussed the Plan's goals and development process and invited community feedback and input on High Injury Network, collision profiles, priority areas, and proposed safety countermeasures to help guide the next steps of the Plan. The public outreach platform was also shared so residents can continue providing input throughout the project. The video and presentation are available on the project website via the QR code or at - www.LivermoreCA.gov/VisionZero

Share your Traffic Concerns by February 11, 2026

Mark intersections and street segments, and provide your safety concerns through QR code on the right.

or visit <https://app.maptionnaire.com/q/226syd2ore37>



Upcoming Community Meeting!

Join us for the next Outreach Meeting in February 2026. Details are provided below!!

Wednesday, February 25 at 7 p.m.

Livermore City Council Chambers
Mendenhall Meeting Room

1016 S Livermore Ave, Livermore, CA, 94550

Note: Please visit the project website for updates on the development of the project.

- Provide feedback and input on High Injury Network
- Community-based traffic concerns (Summary)
- Draft Safety Recommendations
- Action Areas & Implementation Actions

We look forward to hearing from you! For more information, please visit the project website at www.LivermoreCA.gov/VisionZero or through QR code below:

Please scan the QR code to visit our Project Website here!



Focuses on **PREVENTABLE FATAL AND SEVERE CRASHES** rather than eliminating all collisions



Updates collision data and areas of **CONCERN**



Aims to **ESTABLISH SAFE SYSTEMS**



Integrates **HUMAN ERROR** into the approach

